

# Bayesian LAGO for Statistical Detection Problems

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# Outline

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- The statistical detection problem.
- LAGO—An adaptive detection method.
- BLAGO—Bayesian LAGO.
- Conclusions and discussions.

# The Statistical Detection Problem

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- Set-up:  $\{\mathbf{x}_i, y_i\}_{i=1}^n$ ,  $\mathbf{x}_i \in \mathbb{R}^d$  is a vector of predictors,  $y_i \in \{0, 1\}$  is class label. (binary classification?).
- Class frequencies: **extremely unbalanced**.
- Objective: Detect those class-1 observations rather than assign class label to new data.

# Performance Measure

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- Misclassification rate (MR) is not proper.

True label	classification result	
	0	1
0	<b>a</b> (true negative)	<b>b</b> (false positive)
1	<b>c</b> (false negative)	<b>d</b> (true positive)

And the misclassification rate (MIR) is given by

$$\text{MR} = \frac{b + c}{a + b + c + d}$$

- For detection problem, Average Precision (AP) is more suitable.

$$\text{AP} = \frac{1}{n_1} \sum_{i=1}^n \frac{y^{(i)} h(i)}{i}$$

# Examples

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- Google search. Prefer searching algorithms that return the relevant documents as early as possible.  
 $(1,0)$ =(relevant, irrelevant).
- Drug discovery. Prefer a models that detect those active drug agent for a certain disease as soon as possible.  
 $(1,0)$ =(active compound, inactive compound).

# LAGGO: An Adaptive Method

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- LAGGO—Locally Adjusted GO estimate.
- By Bayes' rule:

$$\begin{aligned} p(Y = 1|\mathbf{z}) &= \frac{p(\mathbf{z}|Y = 1)p(Y = 1)}{p(\mathbf{z}|Y = 1)p(Y = 1) + p(\mathbf{z}|Y = 0)p(Y = 0)} \\ &= \frac{af(\mathbf{z})}{af(\mathbf{z}) + 1}, \end{aligned} \tag{1}$$

where  $a = \frac{p(Y=1)}{p(Y=0)}$  and  $f(\mathbf{z}) = \frac{p(\mathbf{z}|Y=1)}{p(\mathbf{z}|Y=0)}$ .

## Step 1 in Estimating $f(\mathbf{z})$

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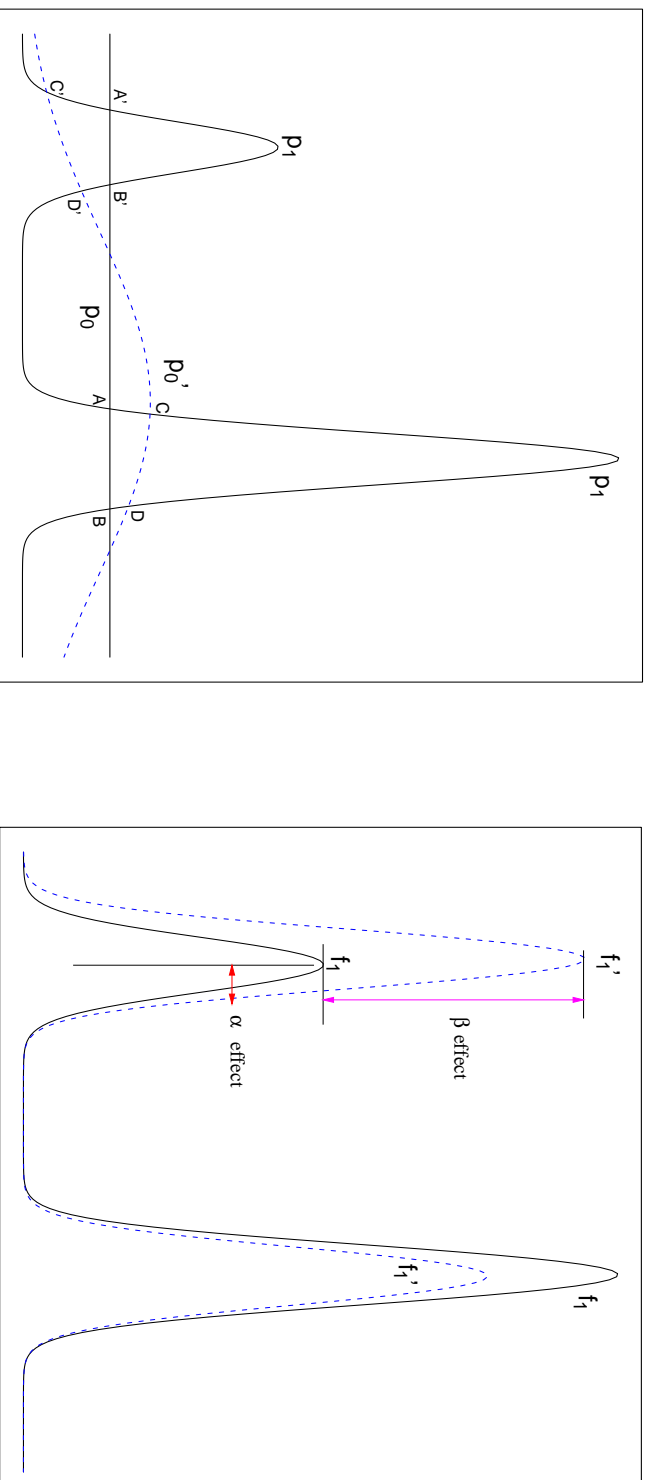
- Estimate  $p(\mathbf{z}|Y = 1)$  by kernel density estimate

$$p(\mathbf{z}|Y = 1) = \frac{1}{N_1} \sum_{i=1}^{N_1} \prod_{j=1}^d \frac{1}{r_{ij}} g\left(\frac{z_j - x_{ij}}{r_{ij}}\right),$$

where  $r_{ij} = \frac{1}{K} \sum_{\mathbf{w} \in N(\mathbf{x}_i, K)} |w_{ij} - x_{ij}|$  is the average distance in the  $j$ -th dimension between a class-1 observation  $\mathbf{x}_i$  and its  $K$  nearest **class-0** neighbors

- If  $p(\mathbf{z}|Y = 0) = C$ ,  $p(\mathbf{z}|Y = 1) \propto f(\mathbf{z})$ , and hence  $p(\mathbf{z}|Y = 1) \propto p(Y = 1|\mathbf{z})$ .

# Examining the ripple effects



**Note:** Left: The density functions of  $p_0$  and  $p_1$ . Right: The posterior distributions.



## Step 2 in Estimating $f(\mathbf{z})$

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- Consider the ripple effects, adjust  $p(\mathbf{z}|Y = 1)$  according to the local density of the class-0 observations, we obtain the LAGO estimate

$$\begin{aligned}\hat{f}(\mathbf{z}) &= \frac{1}{N_1} \sum_{i=1}^{N_1} \prod_{j=1}^d \frac{1}{\alpha r_{ij}} r_{ij}^\beta g\left(\frac{z_j - x_{ij}}{\alpha r_{ij}}\right) \\ &\propto \frac{1}{N_1} \sum_{i=1}^{N_1} \prod_{j=1}^d g\left(\frac{z_j - x_{ij}}{\alpha r_{ij}}\right).\end{aligned}\tag{2}$$

- LAGO paper (2006): *Technometrics*, 48(2), 193-205.

# Motivation of BLAGO

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- Only provides a point estimate, no uncertainty is embodied.
- LAGO score is within  $(0,1)$ , but not a probability.
- A more precise estimate.

# Bayesian Methods in Machine Learning

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- Bayesian Neural Network (Dr. Radford Neal)
- Bayesian Tree (Dr. Hugh Chipman)
- Bayesian K-nearest-neighbor (Dr. Chris Holmes)

# Likelihood Function

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- LAGO score is not probabilistic, change it to probability scale by a logistic transformation

$$\theta_i = p(y_i = 1 | \mathbf{z}_i) = \frac{e^{\beta_0 + \beta_1 \hat{f}(\mathbf{z}_i)}}{1 + e^{\beta_0 + \beta_1 \hat{f}(\mathbf{z}_i)}}, \quad (3)$$

where  $(\mathbf{z}_i, y_i)$  is the  $i$ th test point and  $\beta_1 > 0$ .

- The pseudo-likelihood is

$$L(\boldsymbol{\theta}; \mathbf{Y}) = \prod_{i=1}^n \theta_i^{y_i} [1 - \theta_i]^{1-y_i}. \quad (4)$$

# Prior Distributions

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- $K \sim \text{UNIF}(1, 2, \dots, K_{\max})$ .
- $\alpha \sim \text{UNIF}(0, \infty)$ .
- $(\beta_0, \beta_1) \sim \text{BVN}(\boldsymbol{\mu}_0, \boldsymbol{\Sigma}_0)$  with  $\beta_1 > 0$ .

# MCMC Steps

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**Step 0.** Set the initial  $K_{old}$ ,  $\alpha_{old}$ ;

**Step 1.** Propose new  $K_{new}$  and  $\alpha_{new}$  by

$$K_{new} = K_{old} \pm U[0, 1, 2, 3], \quad \alpha_{new} = \alpha_{old} + N(0, \sigma_\alpha^2).$$

**Step 2.** Generate a random number  $\gamma \sim U(0, 1)$ . Accept the new state  $K_{new}, \alpha_{new}$  if  $\gamma \leq J$  with accepted probability

$$J = \min \left\{ \frac{p(K_{new}, \alpha_{new} | \mathbf{Y})}{p(K_{old}, \alpha_{old} | \mathbf{Y})}, 1 \right\}. \quad (5)$$

**Step 3.** Repeat steps 2 and 3 until burn-in.

# Laplace Approximation

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The well-known Laplace approximation is given by

$$\begin{aligned} I_n &= \int_a^b b(\boldsymbol{\beta}) \exp\{-nr(\boldsymbol{\beta})\} dt \\ &\approx b(\hat{\boldsymbol{\beta}}) \left(\frac{2\pi}{n}\right)^{\frac{p}{2}} (\det \Sigma_{\hat{\boldsymbol{\beta}}})^{\frac{1}{2}} e^{-nr(\hat{\boldsymbol{\beta}})}, \end{aligned} \quad (6)$$

where  $p$  is the dimension of  $\boldsymbol{\beta}$ ; and  $\hat{\boldsymbol{\beta}}$  is the solution to  $\nabla r(\hat{\boldsymbol{\beta}}) = 0$ ; and  $\Sigma_{\hat{\boldsymbol{\beta}}} = [r''(\hat{\boldsymbol{\beta}})]^{-1}$ .

# Evaluating $p(K, \alpha | \mathbf{Y})$

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$$\begin{aligned} p(K, \alpha | \mathbf{Y}) &\propto p(\mathbf{Y} | K, \alpha) \pi(K, \alpha) \\ &\propto \int p(\mathbf{Y} | K, \alpha, \boldsymbol{\beta}) \pi(\boldsymbol{\beta} | K, \alpha) d\boldsymbol{\beta} \\ &= \int L(\boldsymbol{\beta}) \pi(\boldsymbol{\beta}) d\boldsymbol{\beta} \\ &= \int \exp(\mathcal{L}(\boldsymbol{\beta})) d\boldsymbol{\beta} \\ &= \int \exp\left\{-n\left(-\frac{1}{n}\mathcal{L}(\boldsymbol{\beta})\right)\right\} d\boldsymbol{\beta} \\ &\approx (2\pi)^{p/2} e^{\mathcal{L}(\boldsymbol{\beta}^* | K, \alpha)} |H(\boldsymbol{\beta}^* | K, \alpha)|^{-1/2}. \quad (7) \end{aligned}$$

- $\mathcal{L}(\boldsymbol{\beta}^*)$ : Log posterior of  $\boldsymbol{\beta}$  evaluated at the posterior mode  $\boldsymbol{\beta}^*$
- $H(\boldsymbol{\beta}^*)$ : Hessian matrix of the log posterior of  $\boldsymbol{\beta}$  evaluated at  $\boldsymbol{\beta}^*$ .



# Prediction

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Suppose

$$\theta(\mathbf{z}_i | \text{train}, k_0, \alpha_0, \boldsymbol{\beta}_0) = \frac{e^{\mathbf{x}_i^T \boldsymbol{\beta}_0}}{1 + e^{\mathbf{x}_i^T \boldsymbol{\beta}_0}}, \quad (8)$$

where  $\mathbf{x}_i = [1, \hat{f}(\mathbf{z}_i | \text{train}, k_0, \alpha_0)]^T$ . Incorporating uncertainty, the prediction

$$\begin{aligned} \theta(\mathbf{z}_i | \text{train}) &\approx \frac{1}{M} \sum_{j=1}^M \theta(\mathbf{z}_i | \text{train}, k^{(j)}, \alpha^{(j)}) \\ &= \frac{1}{M} \sum_{j=1}^M \int \theta(\mathbf{z}_i | \text{train}, k^{(j)}, \alpha^{(j)}, \boldsymbol{\beta}) p(\boldsymbol{\beta} | \text{train}, k^{(j)}, \alpha^{(j)}) d\boldsymbol{\beta}, \end{aligned}$$

where  $k^{(j)}$  and  $\alpha^{(j)}$  are the  $j$ th ( $j = 1, \dots, M$ ) sample in the converged chain.

# Conclusions and Discussions

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- Strength: BLAGO provides a probabilistic prediction and uncertainty of the prediction.
- Challenges:
  - Choice of the prior distributions.
  - The proposal functions.
  - Performance measure.

# Reparameterization

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- Consider the ripple effect,  $\alpha$ , the kernel function ( $d=1$ ) is

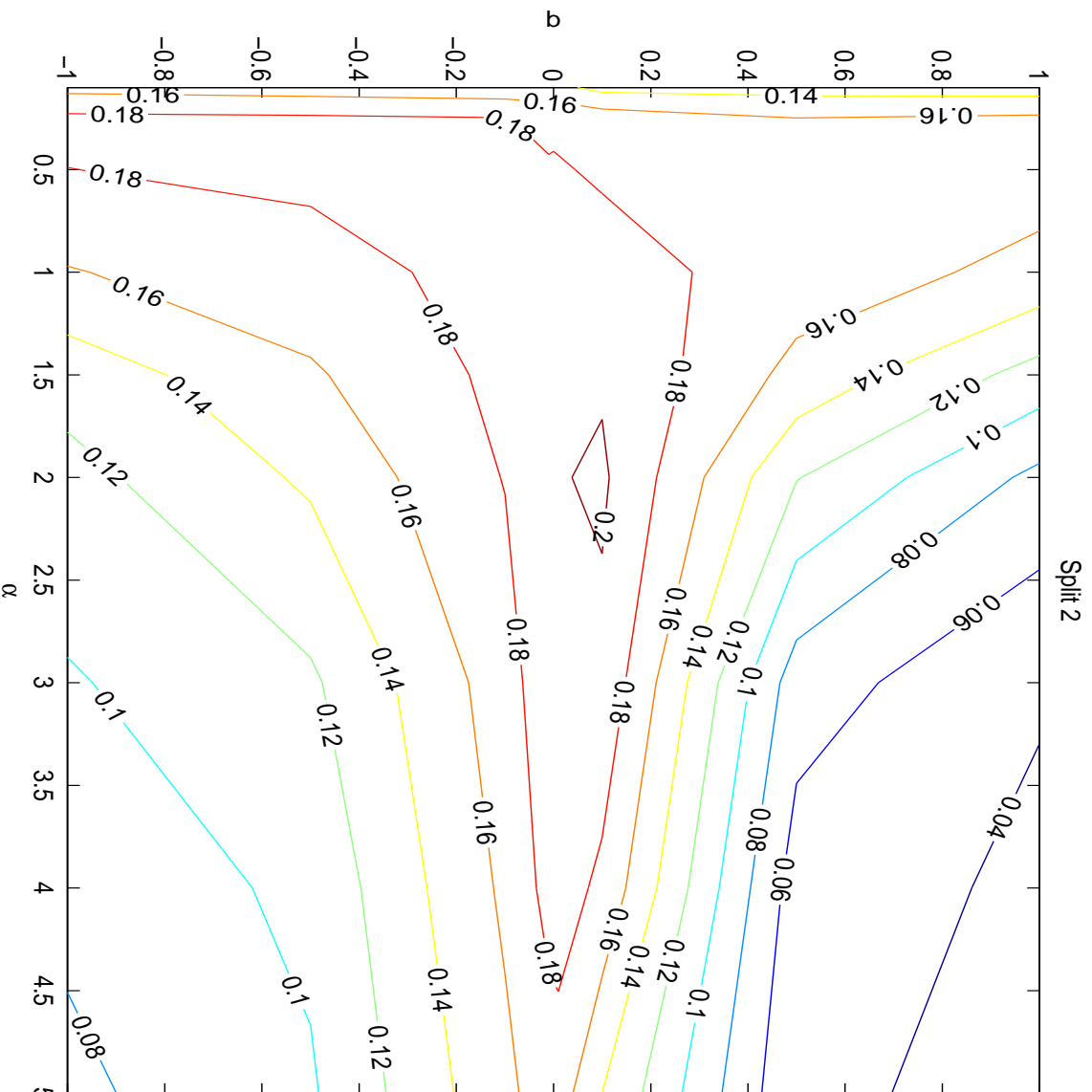
$$\frac{1}{\alpha r_i} g\left(\frac{z - x_i}{\alpha r_i}\right)$$

- Incorporate the other ripple effect,  $\beta$ , the score function is

$$\hat{p}(\mathbf{z}) = \frac{1}{n_1} \sum_{i=1}^{n_1} \left(\frac{1}{\alpha r_i}\right) (\alpha r_i)^\beta g\left(\frac{z - x_i}{\alpha r_i}\right) \propto \frac{1}{n_1} \sum_{i=1}^{n_1} r_i^{\beta-1} g\left(\frac{z - x_i}{\alpha r_i}\right)$$

- An empirical study shows that  $b = \beta - 1 \approx 0$ .

# Average precision maximized around $b \approx 0$



# The NCI database

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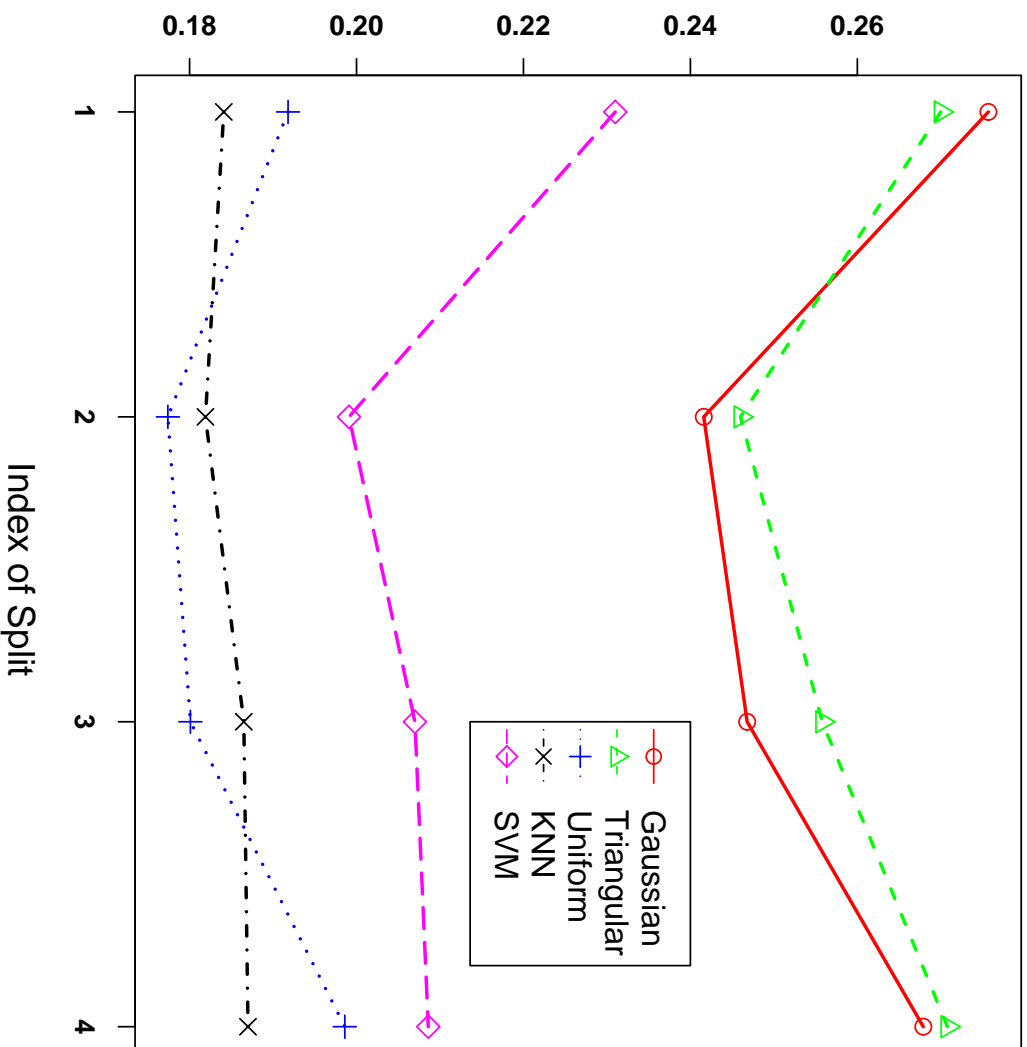
**AIDS Antiviral Data**—from National Cancer Institute (NCI)

- Target—HIV1 virus;
- Response:  $\{0, 1\}$  or  $\{\text{inactive}, \text{active}\}$
- Explanatory variables: Molecular descriptors (BCUT<sub>1</sub>, ..., BCUT<sub>6</sub>).

	Training	Test	
Active	304	304	<b>608</b>
Inactive	14,602	14,602	29,204
Total	14,906	14,906	29,812

# Results and Comparisons

## Average Precision



# A Numeric Summary of Hit Curve

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$$\text{Average Precision} = \frac{1}{n_1} \sum_{i=1}^n \frac{y(i)h(i)}{i}$$

Ranking	True Class Label	Precision
1	1	1/1
2	1	2/2
3	0	
4	1	3/4
5	0	
6	0	

$$\text{AP} = \frac{1}{3} (1/1 + 2/2 + 3/4) \approx 0.9167$$